

Design and analysis of gamma type Stirling engine

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Abstract. This article discusses how to design and manufacture a gamma type Stirling engine. The Stirling engine is an external combustion engine that does not produce any pollution. In this study, we studied the design and manufacturing of industrial Stirling engine. After designing and manufacturing all the parts, the designed Stirling engine has been launched by a 550-watt electric heater and has been tested in two uninsured and insulated modes. In non-insulated mode, the motor had a power of 68.69 watts with a yield of 12.66% and, when the motor is insulated, it had a power of 86.48 watts with a yield of 15.72%.

Keywords: External combustion engine / gamma type / power / Stirling engine

1 Introduction

The Stirling engine is an external combustion engine that has made it easy to repair and maintain the engine in addition to low engine noise and no pollution. On the other hand, the Stirling engine is very simple in terms of mechanism because it does not have any valves. However, this engine has a high sensitivity to friction and fails with the slightest friction. On the other hand, external combustion of this engine has made the engine important in recent years, because in addition to its high efficiency and lack of any pollution, it can function with all kinds of energy. Since the invention of the Stirling engine in 1816 by Robert Stirling, a lot of research has been done on the sterling engine, the first mathematically accepted scheme for analyzing the sterling engine offered by Schmidt 50 years after its invention [1].

This theory considered the ideal gas expansion and contraction process as isothermal and with some simplifications, provided equations for calculating the distribution of pressure as a function of the crank angle, as well as determining the cycle work (first order method). In 1975, Finkellstein [2] developed Schmidt's thermodynamic analysis and presented adiabatic initial analyzes and considered adiabatic condensation and expansion chambers in solving adiabatic equations. Considering this, the equations would not be linear and numerical methods must be used to solve them (second order method).

Hennis et al. [3] at late 2009 addressed the increasing the efficiency of the Stirling Alpha Engine, the SOLO

161 model, using heat exchangers in a cold and hot chamber. They considered eight modes, which the linear arrangement of exchanger tubes had the highest output of 43.66% and the highest output power. They eventually showed that, despite an increase in dead weight, the overall engine efficiency increased by an average of 13%.

Tlili [4] in 2011, using adiabatic process for expansion and contraction chambers applied the Scotch Yoke mechanism on an Alpha-type motor. The swept volume of 24.5 cc, the heating and cooling chamber temperature of 923 and 350 Kelvin, the air agent are the initial data considered for this modeling. The result of this study show the efficiency and output power of the engine in different engine and temperatures conditions, which the average engine power is 48.79 watts.

Rogdakis et al. [5] investigated the thermodynamic and experimental combination of the Stirling engine. The engine under investigation was a SOLO V161 that was investigated by a hydrogen operating fluid at a maximum pressure of 150 times. The swept volume of this engine is 160 cc at 1500 rpm. The output power obtained (numerical) is a power output of at least 1.6 KW electrical and 8.8 KW heat power. Also, the range of motor efficiency is reported from 12.6 to 20.23 and the thermal efficiency is in range of 61.01–69.31, which indicated a maximum error of 20% to experimental data.

Valenti et al. [6], in 2013, addressed numerical and empirical studies of the Stirling engine system for home use. The swept volume of the hot and cold chamber was 27.4 and 28.4 cc, respectively, and the nitrogen was used as operating fluid. The results indicated an electrical capacity of 1 KW and a heating capacity of 8 KW, indicating a difference of 4% between experimental and simulated results.

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Table 1. Component specifications of Stirling engine.

N	Piece details	Piece material	D_i (mm)	D_o (mm)	Length (mm)	Weight (gr)
1	Displacement piston	aluminum	63	73	46	230
2	Displacement cylinder	aluminum	75	118	88	795
3	Displacement cylinder bushing	Brass	5	30	30	71
4	Displacement piston connecting rod	Steel	–	5	110	14
5	Power cylinder head	Steel	–	–	20	2907
6	Power cylinder	Steel	50	68.2	69.5	920
7	Power piston	Steel	44.4	49.95	50	308
8	Power connecting rod	Steel	–	–	106	40
9	Crankshaft	Steel	–	10	110	68
10	Flywheel	Steel	–	184	12.2	900
11	Displacement cylinder connecting rod	Brass	–	–	5	66

Table 2. General specifications of Stirling engine.

Dead volume of displacement cylinder	66 cc	Displacement cylinder swept volume	103 cc
The dead volume of the power cylinder	18 cc	swept volume of the power cylinder	86 cc
Total weight	9.5 kg	cylinders volume ratio	1.2
Operating fluid	air		

designed and built. low weight of parts, appropriate thermophysical properties, reasonable price for selected material, and temperature range of the piece were considered in designing all the pieces; the specifications of the main pieces are given in Table 1. The overall engine profile is also shown in Table 2.

$$W_{\text{out}} = F \cdot P \cdot \omega \cdot V_{\text{swd}} \cdot \frac{T_h - T_C}{T_h + T_C} \quad (2)$$

$$W_{\text{out}} = Be \cdot P \cdot \omega \cdot V_{\text{swd}} \quad (3)$$

$$\eta_e = \left(1 - \frac{T_C}{T_h}\right) \cdot C \cdot \eta_H \cdot \eta_M \cdot Z \quad (4)$$

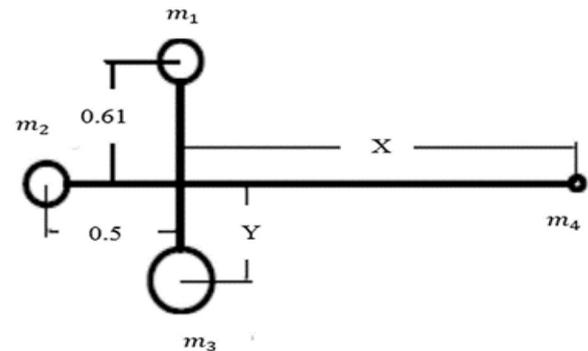
2.2 Engine balance

In this engine displacement crank and power crankshaft are two nonbalance masses, each with a 90-degree angle. Thus, according to Figure 3, the engine is balanced by adding two masses along the lines of the nonbalance masses.

To do this, if center of mass of the nonbalance objects is obtained the mass and the distance of the unknown masses, can be obtained from equation (5) for the x axis as well as equation (6) for the y axis.

$$X : m_2 \cdot r_2 = m_4 \cdot x, \quad m_4 \cdot x = 61 \quad (5)$$

$$Y : m_1 \cdot r_1 = m_3 \cdot y, \quad m_3 \cdot y = 60. \quad (6)$$

**Fig. 3.** Unbalance and balancing objects.

Thus, taking into account x and y , the balancing masses m_3 and m_4 are obtained.

$$y = 0.39 \text{ mm}, \quad m_3 = 190 \text{ gr}$$

$$y = 13.65 \text{ mm}, \quad m_4 = 44 \text{ gr}$$

2.3 Electrical heater

The engine was first launched by an electric heater placed inside the displacement cylinder. In fact, the dead volume of the displacement cylinder mentioned in Table 2 is due to the presence of this heater. The maximum heater heating power is about 550 watts. It is also possible to reduce the input power using the electric dimmer. The final form of the

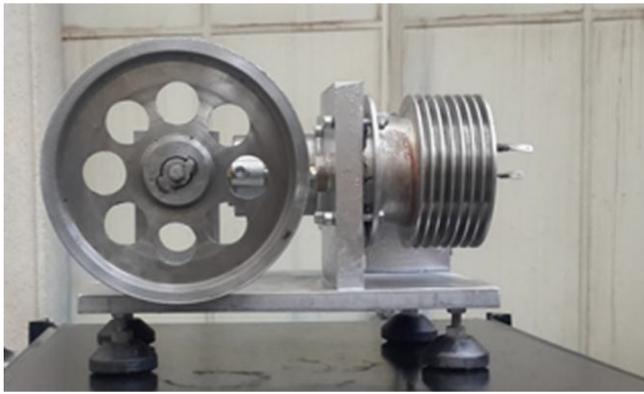


Fig. 4. The Stirling engine built.

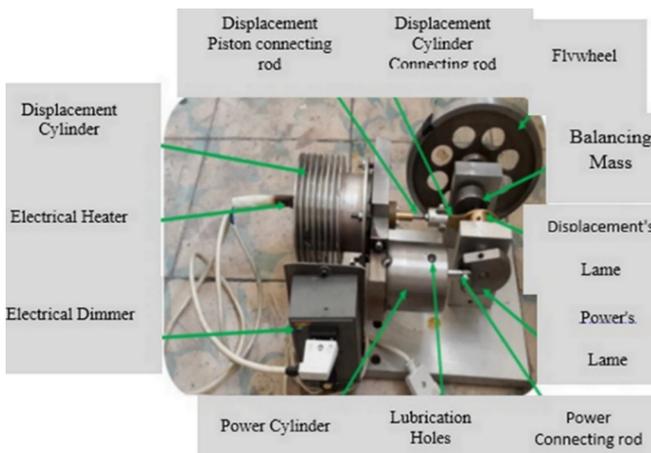


Fig. 5. Details of the Stirling engine.

engine is shown in Figure 4. The engine details are also shown in Figure 5.

3 Results

The experiments were carried out in two insulated and non-insulated hot cylinder displacement cases. In each test, the power output of the motor is obtained by reducing the input voltage (V) by the dimmer. In each test, the temperature of the cold and hot chambers, rotation, and torque of the engine is measured. The maximum output torque of the motor in this mode is 23.1 N.m. at 541 rpm. In fact, the maximum output power of an engine in a non-insulated state is 69.68 watts. Figures 6 and 7, respectively, show the output power and motor efficiency in terms of the temperature of the hot chamber in non-insulated conditions.

In non-insulated mode, some of the power input to the engine is lost through the transfer from the hot chamber of displacement cylinder. Therefore, the engine was tested once again when the hot chamber of displacement cylinder (two third of cylinder displacement) was insulated. The maximum torque in this mode is 1.34 N.m. In this case, the engine speed is 616 rpm, so the maximum output

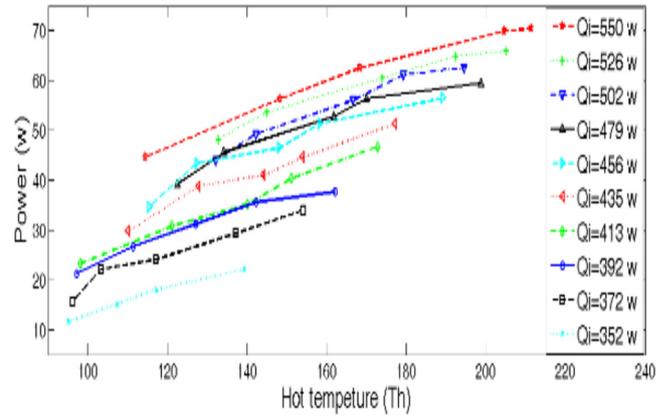


Fig. 6. Diagram of temperature-power Stirling engine without insulation.

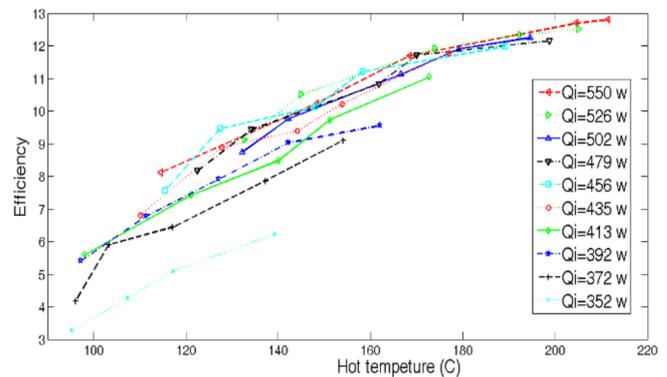


Fig. 7. Diagram of Temperature-efficiency Stirling engine without insulation.

power of the engine in the uninsulated state is 86.44 watts. The engine power and efficiency in terms of the temperature of the hot chamber in the case where engine is insulated are shown in Figures 8 and 9.

4 Conclusion

A more accurate comparison of the results indicated a quantitative difference between the values obtained for power and efficiency with calculated values of Beale, West and Carlquist's methods.

Due to the fact that the sterling engine fails with the slightest friction, therefore, in addition to increasing the diameter of the displacement cylinder, which reduces the length of the displacement course, the lubrication operation should be carried out regularly on the cylinder because the maximum friction of the motor at the contact point of the power cylinder. Also, increasing the power of the electric heater, and thereby increasing the temperature of the hot chamber, will increase the pressure, resulting in increased power and engine efficiency. On the other hand, the engine's balance has significantly reduced the vibration of the engine so that the engine had the least vibration in operating condition, because a small amount of unbalance prevents the engine from operating.

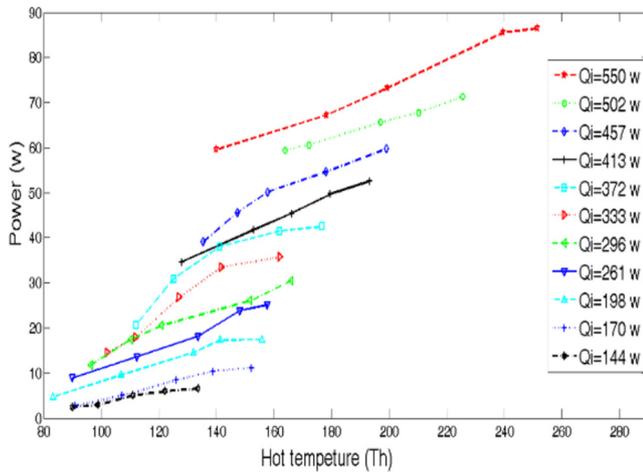


Fig. 8. Diagram of temperature-power Stirling engine with insulation.

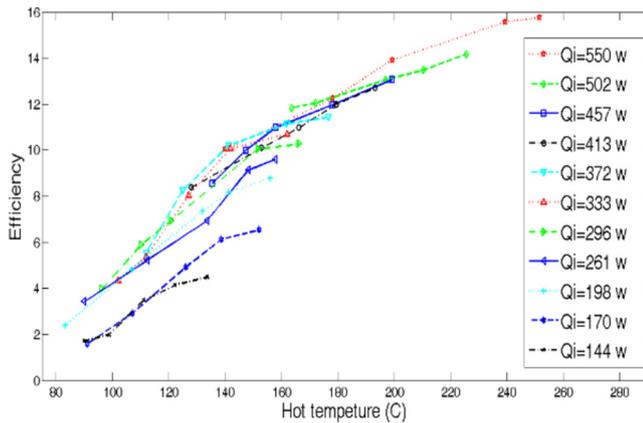


Fig. 9. Diagram of temperature-efficiency Stirling engine with insulation.

By inserting an electric heater into the cylinder, the heat loss is reduced greatly, because output of the heater directly is transferred to the operating fluid in hot chamber of displacement cylinder, which increases the engine efficiency in different conditions.

Nomenclature

W	Output power, watt
Q	Transfer rate heat, watt
T	Temperature, K
F	West's coefficient
P	Pressure, bar
V	Volume, m^3
ω	Rotational speed, Hz
B_e	Beale's coefficient

C	Coefficient ratio to Carnot returns (0.65–0.75)
Z	Correction factor (0.95)
m	Mass (gr)
r	Massage center distance to crankshaft axis, m
D	Diameter, m
η_C	Cycle efficiency
η_H	Heating efficiency (0.85–0.9)
η_M	Engine mechanical efficiency (0.85–0.9)
η_e	Engine efficiency

Subscripts

out	Output
o	Outer side
i	Inner side
h	Hot
c	Cold
swd	Sswept of displacement cylinder

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