

Erratum to: Inertia matching of CNC cycloidal gear form grinding machine servo system

Erratum to: Mechanics & Industry 2023, 24, 31 – <https://doi.org/10.1051/meca/2023020>

Jubo Li^{1,2}, Jianxin Su^{1,2,*}, Ming Gao³, Donghui Zhao⁴, Leilei Zhang³, Dinghe Wang⁴, Fusheng Shi⁴, and Chenxiao Yan¹

¹ School of Mechatronics Engineering, Henan University of Science and Technology, Luoyang, Henan 471003, PR China

² Advanced manufacturing of mechanical equipment Henan Collaborative Innovation Center, Henan University of Science and Technology, Luoyang, Henan 471003, PR China

³ First Tractor Company Limited, Luoyang, Henan 471004, PR China

⁴ Zhong Bang Superhard tools Co. Ltd, Zhengzhou, Henan 450001, PR China

Received: 5 September 2023 / Accepted: 5 September 2023

Regarding the article [J. Li, J. Su, M. Gao, D. Zhao, L. Zhang, D. Wang, F. Shi, Inertia matching of CNC cycloidal gear form grinding machine servo system, 24, 31 (2023)], published on August 28th 2023, this erratum corrects a mistake happened during the production of the paper.

One of the co-authors was missing: the eighth and last co-author of this article is Chenxiao Yan, whose affiliation is School of Mechatronics Engineering, Henan University of Science and Technology, Luoyang, Henan 471003, China.

The Publisher apologizes for this mistake.

Cite this article as: J. Li, J. Su, M. Gao, D. Zhao, L. Zhang, D. Wang, F. Shi, C. Yan, Erratum to: Inertia matching of CNC cycloidal gear form grinding machine servo system, Mechanics & Industry **24**, 35 (2023)

* e-mail: 9903437@haust.edu.cn